

RC-001

Radio Control

User Manual



rev: 261016
Made in Taiwan

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INTRODUCTION

The **RC-001 Radio Control** isn't just a controller; it's a full-fledged pilot's command center. High-precision Hall Sensor gimbals, a crisp 1.3" OLED display, and multi-protocol support—including ELRS 500mW—deliver pinpoint control whether you're racing, freestyling, or exploring long-range. Compact, lightweight, and powerful, the RC-001 gives the "locked-in" feel usually reserved for radios twice its size.

PACKAGE CONTENTS

- 1x RC-001
- 1x User Manual

FEATURES

- Internal RF: ELRS 915M or 2.4G
- External RF: optional
- Working Voltage: DC 5.5V – 8.4V
- Display: 1.3" OLED (128*64 Resolution)
- Trainer Port: 3.5mm standard PPM
- Battery Charger: 2 x 18650
- Hardware Reference: EdgeTX
- Dimensions: 160 * 128 * 68 mm
- Weight: 330g (with batteries)

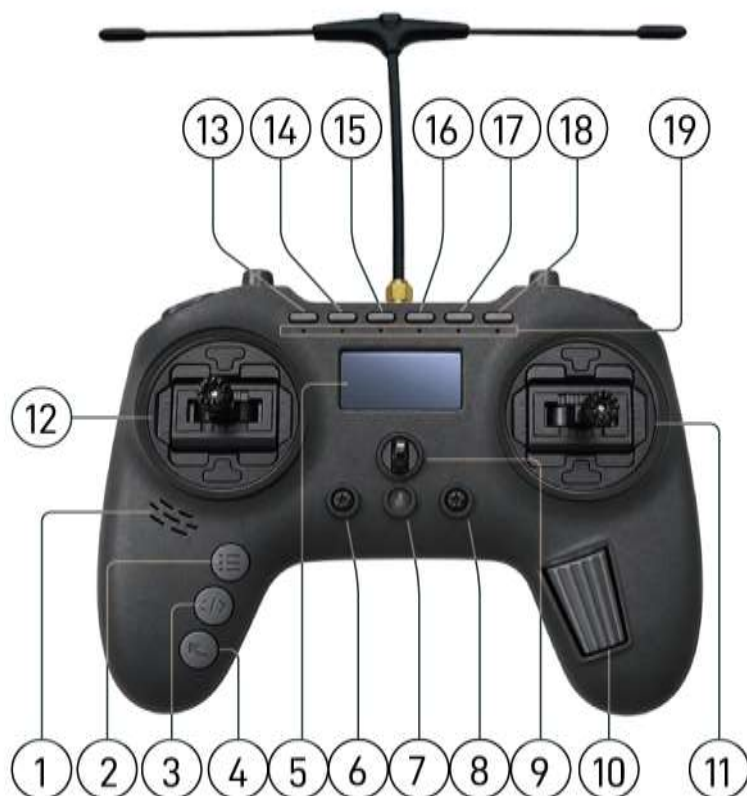
RADIO OVERVIEW

Top Panel



1. SD – unlock switch port D
2. SB – lock switch port B
3. SL – rotary switch port L
4. SF – 3-segment switch port F
5. Trainer port
6. Boot button – FW update use
7. USB-C
8. SE – 3-segment switch port E
9. SK – rotary switch port K
10. SA – lock switch port A
11. SC – unlock switch port C
12. SMA female connector

Front Panel



1. Speaker output
2. Option Button
3. Select Button
4. Return Button
5. 1.3" OLED white color
6. 5-direction button^{a)}
7. Power Button^{b)}
8. 5-direction button^{c)}
9. Neck strap hook
10. Menu Wheel & Enter Button
11. Single-axis self-centering(mode 1) or self-centering(mode 2) joystick
12. Single-axis self-centering(mode 2) or self-centering(mode 1) joystick
13. Downshift power amplifier(INT & EXT RF)
14. Downshift packet frequency(INT & EXT RF)
15. Reserved
16. Reserved
17. Upshift packet frequency(INT & EXT RF)
18. Upshift power amplifier(INT & EXT RF)
19. Welcome LED & RF rssi LED^{d)}

Note:

a)

Direction / Action	Function Description
Up (□)	Shifts the left joystick's vertical center position upward (□)
Down (□)	Shifts the left joystick's vertical center position downward (□)
Left (□)	Shifts the left joystick's horizontal center position downward (□)
Right (□)	Shifts the left joystick's horizontal center position upward (□)
Center (Press)	Unlocks switch port G

b)

Power Status	LED Color	Description
Power OFF	Solid Green	Charging complete / Fully charged
	Solid Blue	Charging
	Blinking Red	Battery abnormal
Power ON	Solid Green	RF link OK
	Solid Yellow	RF standby
	Solid Cyan	Trainer link active
	Solid Orange	RF link quality >50% & < rssi 80%(□) or rssi 65%(-)
	Solid Red	RF link quality <50%

* Priority Note: For Power ON indicators, Solid Green has a higher priority than Solid Cyan (Solid Green > Solid Cyan). If both states are active simultaneously, the LED will display Solid Green

**Power On: Press and hold the power button until all welcome LEDs light up in sequence, then release

Power Off: Press and hold the power button until all welcome LEDs go out in sequence.

c)

Direction / Action	Function Description
Up (□)	Shifts the right joystick's vertical center position upward (□)
Down (□)	Shifts the right joystick's vertical center position downward (□)
Left (□)	Shifts the right joystick's horizontal center position downward (□)
Right (□)	Shifts the right joystick's horizontal center position upward (□)
Center (Press)	Unlocks switch port H

d)

- When the power button is pressed, the LEDs will light up sequentially from left to right.
- The 6 LEDs are arranged from left to right as L1, L2, L3, R3, R2, and R1. They indicate the Link Quality according to the following ranges:

Link Quality (%)	Active LEDs (Left to Right)
0%	All LEDs OFF
1% – 16%	L1
17% – 32%	L1, L2

33% – 48%	L1, L2, L3
49% – 64%	L1, L2, L3, R3
65% – 80%	L1, L2, L3, R3, R2
81% – 100%	L1, L2, L3, R3, R2, R1

Rear Panel



1. Battery slot
2. External RF use
3. Battery slot

OPERATION

1. Startup & Safety Warnings

For safety reasons, the transmitter runs a self-diagnostic routine every time it is powered on. If any critical controls are not in their safe or neutral positions, the system will temporarily halt the startup sequence and trigger an alert screen.

- Throttle Warning

If the throttle stick is not at its lowest position when the transmitter is turned on, the system will display a **THROTTLE WARNING** screen with a visual alert icon. You can either press any key to skip directly, or set the throttle stick to the lowest position to bring up the "THROTTLE OK" screen and then press any key to skip.



- Button and Wheel Operation

- a) Menu Page Switching: Press the Option button to cycle through the main functional pages.
- b) Item Selection: Scroll the Menu Wheel to browse the desired menu item to first row or setting field on the current page
- c) Cursor Movement: Press the Select button to select a field and bring up a solid white square cursor (press the Select button repeatedly to cycle through and move the cursor between adjustable fields).
- d) Value Adjustment: Scroll the Menu Wheel/ENT again to change the values or modify the current setting
- e) Confirmation: Press the Menu Wheel & enter button to confirm your selection and complete the setup.

(Note: You can press the Return button at any time to cancel changes and return to the previous screen.)

2. Main Interface & Telemetry Monitoring

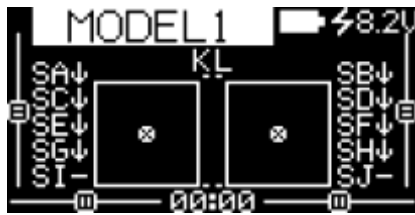
This interface provides four interchangeable main interface views on its 1.3" OLED display, allowing pilots to monitor real-time telemetry, battery health, channel outputs, and stick/switch positions at a glance.

On the home screen, short press the Select button to cycle through the four available monitoring interfaces detailed below.

- Main Joystick & Switch Status (Home Screen)

- Status Bar: Displays the current model name, a graphic battery icon (✓ is the battery charging icon), and the precise transmitter voltage.
- Joystick Position Monitors: Two center squares visually track the real-time position of the left and right high-precision Hall Sensor joystick using crosshair indicators.
- Trim & Potentiometer Indicators
 - The vertical and horizontal sliders on the outer edges show the current digital trim positions.

- The top text indicators (K, L) show the relative positions of the rotary pots or sliders.
- Bottom time display time.
- Switch Position List: Tracks the physical status of toggles SA through SH using directional arrows (↓ for down, - for central, ↑ for up)



- Channel Output Bar Chart (CH 1-16)

- Visual Output Bars: Displays a real-time graphical representation of the output across your control channels.
- Layout: Displays channels 1 to 16 horizontally. Dash lines mark the center and maximum/minimum boundaries, though interpretation varies by channel type:
 - General Channels: Vertical bars extending upward represent positive channel values, while bars extending downward represent negative channel values. Dash lines mark the center (0%) and maximum/minimum ($\pm 100\%$) boundaries.
 - Throttle Channel: Vertical bars represent the absolute throttle position. Dash lines mark the center (50% throttle), the top boundary (100% maximum throttle), and the bottom boundary (0% minimum throttle).



- Numerical Channel Value Matrix

- Precise Channel Data Percentage: Provides an explicit numerical view of the exact output values being transmitted to the receiver across all 16 channels.
- Layout: Organized in a clean 4x4 grid (Channels 1-4, 5-8, 9-12, and 13-16).
- Data Mapping Examples:
 - CH1: +100 (Maximum positive throw)
 - CH2: +50 (Half positive throw)
 - CH3: 0 (Lowest position)
 - CH4: -50 (Half negative throw)

Channel			
1 +100	5 09	013	0
2 +50	6 010	014	0
3 07	011	015	0
4 -50	8 012	016	0

- Stick & Physical Switch Matrix (Stick & SW)
 - Raw Input Diagnosis: Displays the raw hardware input values coming directly from your primary sticks, pots, and auxiliary switches before mixing formulas are applied.
 - Primary Flight Sticks (Left Column): (Ex: plane type)
 - AIL (Aileron): Displays current roll stick value.
 - ELE (Elevator): Displays current pitch stick value.
 - THR (Throttle): Displays current throttle position value (0 representing mid-throttle in this view).
 - RUD (Rudder): Displays current yaw stick value.
 - Auxiliary Switches & Pots (Columns 2-4): Shows the current status values ranging from -100 to +100 for assignable hardware toggles and pots (labeled A through L).

Stick & SW			
AIL	+100	A+100	E+100
ELE	+50	B+100	F+100
THR	0	C+100	G+100
RUD	-50	D+100	H+100

3. Model Selection & Channel Assignment

- Channel Assignment (CH1-CH16)

The CH Assign menu handles the physical-to-digital mapping. It determines which flight stick or toggle switch controls which output channel sent to the receiver.
- Aircraft Platform Type Assignment Table

Platform Type	Default Control Assignments & Mixing Formulas	Available Switches
Plane	AIL, ELE, THR, RUD	SA, SB, SC, SD, SE, SF, SG, SH, SI, SJ, SK, SL
Multi	ROL, PIT, THR, YAW	SA, SB, SC, SD, SE, SF, SG, SH, SI, SJ, SK, SL
Delta	ELE+AIL, ELE-AIL, THR, RUD	SA, SB, SC, SD, SE, SF, SG, SH, SI, SJ, SK, SL
V-Tail	AIL, ELE+RUD, THR, ELE-RUD	SA, SB, SC, SD, SE, SF, SG, SH, SI, SJ, SK, SL
Flape	SA(B)(E)(F)+AIL, ELE, THR, RUD, SA(B)(E)(F)-AIL	(SA), SB, SC, SD, SE, SF, SG, SH, SI, SJ, SK, SL
Heli	P-E+A, P+E, THR*, RUD, P-E-A	SA, SB, SC, SD, SE, SF, SG, SH, SJ, SK, SL

- Data Options:
 - General: Normal (forward) channel output
 - Reverse: Inverted (reversed) channel output

CH	assign	data
1	AIL	general
2	ELE	general
3	THR	general
4	RUD	general
5		general
6		general

- Model Selection (Model 1-Model 8)

The Model List menu allows you to manage multiple aircraft profiles, customize their names character by character, and define the aircraft platform type

- Aircraft platform type:
 - Plane: Traditional fixed-wing aircraft
 - Multi: Multirotor configurations (quadcopters, hexacopters, etc.)
 - Delta: Delta wings and tailless flying wings
 - V-Tail: Aircraft utilizing a V-tail control surface layout
 - Flape: Fixed-wing aircraft using dual-aileron flaperon mixing
 - Heli: Traditional RC helicopters

model	name	type
1	MODEL1	Plane
2	MODEL2	Plane
3	MODEL3	Plane
4	MODEL4	Plane
5	MODEL5	Plane
6	MODEL6	Plane

4. Radio Frequency (RF) Link Setup

- Internal RF Setup (Built-in Module Configuration)
 - RF mode: Set to ELRS to manage link properties for native ExpressLRS receivers (non-adjustable).
 - baudrate: Controls the internal data bus speed between the radio operating system and the internal module. It is set to 400k by default for optimized latency.
 - packet freq.: Sets the link transmission refresh rate (measured in Hz). It is set to 50Hz by default to prioritize signal penetration. When the Pause & Power item is set to on, selectable options include 25, 50, 100, or 200.
 - ssi set / Transmission Power: Controls the active telemetry threshold and output wattage. The operational power is set to 100mW by default. When the Pause & Power item is set to on, selectable options include 50mW, 100mW, 250mW, or 500mW.
 - rssi low alarm: Selecting this field allows you to cycle through three signal trend options to determine when the low signal warning triggers:
 - ☐ (50%): Triggers an audible alert and vibration when the signal trend drops below a 50% threshold
 - ☐ (65%): Triggers an audible alert and vibration when the signal trend drops below a 65% threshold
 - ☐ (80%): Triggers an audible alert and vibration when the signal trend drops below a 80% threshold.

After choosing your preferred baseline trend, you can input specific decibel threshold limits to trigger audible signal warnings and vibration, ensuring you receive timely alerts

well before a critical failsafe occurs.

- Pause: Toggles the standby mode of the internal RF signal (off or on). Turn on to temporarily disable internal transmission when configuring settings on the bench.
- power / Module Power: Completely switches the power supply to the internal RF module (on or off).
- RF freq: Explicitly configures the target hardware operating frequency band of your internal module (915M or 2.4G)
- RF into boot: A utility selection line used to force the internal ExpressLRS module into bootloader mode for firmware updates. When the Pause & Power item is set to on, selectable options include N or Y.

```
Internal RF setup
RF mode          ELRS
baudrate         400k
packet freq.     50
ssi set          100mW
rssi low alarm   ↓
pause            off
```

- External RF Setup (Expansion Bay Configuration)
 - RF mode: Set to ELRS to manage link properties for native ExpressLRS external modules (non-adjustable).
 - baudrate: Controls the data transfer speed running to the external module slot. Options include 115K, 400K, 921K, 1870K, 2250K, 3750K, and 5250K to optimize signal processing latency.
 - packet freq.: Sets the link transmission refresh rate (measured in Hz). It is set to 50Hz by default to prioritize signal penetration. When the Pause & Power item is set to on, selectable options include 25, 50, 100, or 200.
 - ssi set / Transmission Power: Controls the active telemetry threshold and output wattage. The operational power is set to 100mW by default. When the Pause & Power item is set to on, selectable options include 1W, 2W, 10mW, 25mW, 50mW, 100mW, 250mW, or 500mW.
 - rssi low alarm: Selecting this field allows you to cycle through three signal trend options to determine when the external module low signal warning triggers:
 - □ (50%): Triggers an audible alert when the external signal trend drops below a 50% threshold
 - - (65%): Triggers an audible alert when the external signal trend drops below a 65% threshold
 - □ (80%): Triggers an audible alert when the external signal trend drops below an 80% threshold

After choosing your preferred baseline trend, you can input specific decibel threshold limits to customize independent alert triggers for your expansion hardware well before a failsafe occurs

- Pause: Temporarily pauses active link tracking output for the external slot (off or on)
- power / Module Power: Completely switches the power supply to the external RF module (on or off).
- RF freq: Explicitly configures the target hardware operating frequency band of your external module (915M, 2.4G, or dual)
- RF into boot: A utility selection line used to force the internal ExpressLRS module into bootloader mode for firmware updates. When the Pause & Power item is set to on,

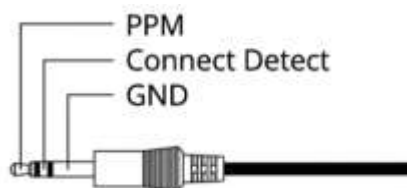
selectable options include N or Y.

```
External RF setup
RF mode      ELRS
baudrate     400k
packet freq. 100
ssi set      500mW
rssi low alarm ↓
pause       off
```

5. Trainer Mode Settings

- Parameter Configurations
 - mode: Defines the active identity profile of this radio. Options include coach (configures the RC-001 as the instructor's master command radio with full override authority over the incoming student control link) or trainee (configures the radio as the student device to output control signals to the master radio).
 - ch start: Specifies the starting data slot threshold for the student input channels. Options range from 1 to 9 (defaulted to 1), designating which the channel begins reading the student's channel.
 - ch num: Sets the total consecutive number of channels assigned to the student control loop. Options range from 1 to 8 (defaulted to 4) to map the desired flight controls and auxiliary switches to the trainee
 - sw: Assigns the physical emergency takeover hardware toggle switch. Options are SA or SB (defaulted to SA). When this switch is engaged, control transfers from the student; releasing or flipping the switch instantly pulls control back to the instructor
 - link: Configures the hardware communication connection protocol between the two radios. Options are wired (enables data routing through the physical 3.5mm standard PPM link port)* or wireless (enables a cable-free over-the-air trainer link connection).
 - enable: The master master-switch for the trainer function state. Options are N (No/Disabled) to turn off the function or Y (Yes/Enabled) to activate the tracking link during training flights.

*tip ring sleeve



**When trainer enable and connect trainee side RF power will auto close

```
Trainer setup
mode      coach
ch start  1
ch num    4
sw        SA
link      wired
enable    N
```

6. Advanced Mixing & Tail/Heli Configurations

- Fixed-Wing Mixing Rates (Mixrate Setup)

The Mixrate setup menu allows you to manage control surface mixing ratios for specialized fixed-wing airframes.

- delta: Sets the elevon mixing percentage for delta wings or flying wings. Options range from 1% to 100% (defaulted to 50%).
- vtail: Sets the V-tail mixing percentage, combining elevator and rudder movements onto two tail servos. Options range from 1% to 100% (defaulted to 50%).
- flape-flap: Configures the flaperon deployment ratio, defining how far both surfaces drop symmetrically when used as flaps. Options range from 1% to 100% (defaulted to 50%).
- flape-ail: Adjusts the dynamic roll authority of the flaperons when working as primary ailerons. Options range from 1% to 100% (defaulted to 50%).
- flape sw: Assigns the physical auxiliary hardware switch to deploy or toggle the flaperon/flap modes. Options include SA, SB, SE, or SF (defaulted to SF).



```
Mixrate setup
delta          50%
vtail          50%
flape-flap     50%
flape-ail      50%
flape sw       SF
```

- Helicopter Main Parameter Setup (Heli Setup - Mechanicals)

The initial sub-menu under Heli setup defines the primary hardware configurations and safety controls for collective pitch model setups

- swash type: Specifies the mechanical configuration of your helicopter's swashplate. It defaults to 3s120 (3 servos, 120-degree eCCPM layout). Selectable options include 3S120, 3S140, 1S90, or 3S90.
- swash ring: Sets the electronic cyclic ring limiting percentage (defaulted to 100%) to prevent physical binding of the servos at extreme stick corners. The adjustable range is from 1% to 125%.
- pitch mix rate: Controls the overall collective pitch travel range and direction relative to swashplate movement (set to +60%). The adjustable range is from -125% to +125%.
- ele mix rate / ail mix rate: Defines the cyclic throw authority and travel orientation for Pitch/Elevator and Roll/Aileron inputs (both defaulted to +50%). The adjustable range for both items is from -125% to +125%.
- THR hold sw: Assigns the critical physical throttle hold / motor safety cut-off switch (mapped to SA). Selectable options include SA or SB.
- flight mode sw: Assigns the 3-position physical flight mode switch (mapped to SE) used to toggle between Normal and Idle-up 1/2 modes. Selectable options include SE or SF.
- flight mode dir: Sets the directional tracking orientation parameter for active flight mode logic (configured to N12). Selectable options include N12, N21, or 1N2.

```

Heli setup
swash type      3s120
swash ring      100%
pitch mix rate  + 60%
roll mix rate   + 50%
ail mix rate    + 50%
THR hold sw     SA

```

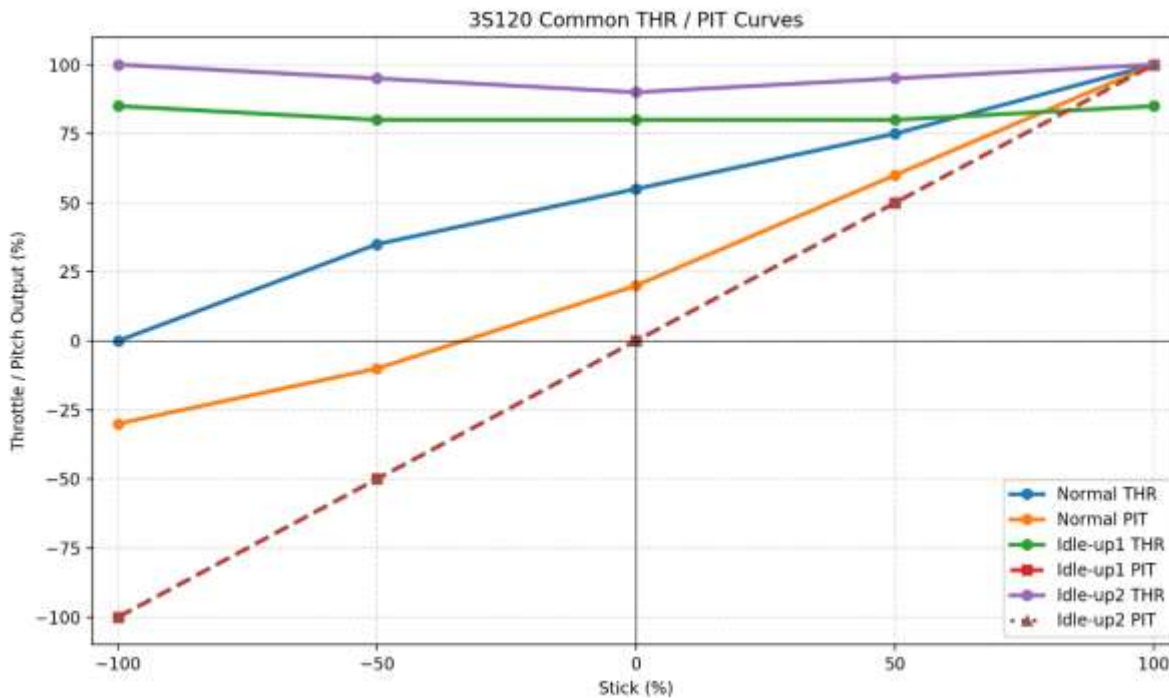
- 5-Point Throttle & Collective Pitch Curves (THR/Pitch Curve Matrix)

The THR/Pitch curve sub-menu utilizes an interactive diagnostic interface. Moving your physical throttle stick updates the stick value indicator line in real-time, allowing you to directly program the multi-point throttle (THR) and collective pitch (PIT) curves across three separate flight profiles (normal, idleup1, and idleup2).

The layout maps the 5 critical stick calibration points as follows:

Stick Position	Curve Parameter Group	Normal Mode (normal)	Stunt Mode 1 (idleup1)	Stunt Mode 2 (idleup2)	Flight Mechanics Application
stick: -100 (Fully Closed)	THR (Throttle) PIT (Pitch)	0 -30	75 -100	85 -100	Normal: Motor off, mild negative pitch. Idle-up: High RPM with full inverted pitch authority.
stick: -50 (Low-Mid)	THR (Throttle) PIT (Pitch)	35 -10	80 -50	90 -50	Establishes smooth transient tracking values from full negative to mid-stick hover configurations.
stick: 0 (Dead Center)	THR (Throttle) PIT (Pitch)	55 +20	85 0	95 0	Normal: Hover setup. Idle-up: V-curve matching engineered for 0° zero-pitch 3D baseline.
stick: +50 (Mid-High)	THR (Throttle) PIT (Pitch)	75 +60	80 +50	90 +50	Manages high-precision resolution scaling between stationary hovering and extreme climbing rates.
stick: +100 (Fully Open)	THR (Throttle) PIT (Pitch)	100 +100	75 +100	85 +100	Normal: Linear maximum engine push. Idle-up: V-curve throttle profile with maximum collective lift throw.

Visual Curve Reference



- Solid Lines: Represent Throttle (THR) outputs across Normal (Blue), Idle-up 1 (Green), and Idle-up 2 (Purple) modes
- Marker Lines: Represent Collective Pitch (PIT) outputs, highlighting the linear setup for 3D acrobatics in Idle-up modes (Red dashed line) versus a gentler curve for stable hovering in Normal mode (Orange line).

7. General System Configuration

- Parameter Descriptions
 - model select: Manages global profile switching. This parameter allows you to change the active model index globally across the entire operating system. The configurable range is from 1 to 8.
 - trim step: Adjusts the interval of the digital trim switches. A smaller step size allows for finer, high-precision balancing of the aircraft's control surfaces. The configurable range is from 1 to 10.
 - L stick hori.L: Configures the parameter or calibration state for the left joystick's horizontal left directional tracking. Selectable options include N or Y.*
 - L stick hori.H: Configures the parameter or calibration state for the left joystick's horizontal right directional tracking. Selectable options include N or Y.*
 - L stick vert.L: Configures the parameter or calibration state for the left joystick's vertical downward directional tracking. Selectable options include N or Y.*
 - L stick vert.H: Configures the parameter or calibration state for the left joystick's vertical upward directional tracking. Selectable options include N or Y.*
 - R stick hori.L: Configures the parameter or calibration state for the right joystick's horizontal left directional tracking. Selectable options include N or Y.*
 - R stick hori.H: Configures the parameter or calibration state for the right joystick's horizontal right directional tracking. Selectable options include N or Y.*
 - R stick vert.L: Configures the parameter or calibration state for the right joystick's vertical downward directional tracking. Selectable options include N or Y.*

- R stick vert.H: Configures the parameter or calibration state for the right joystick's vertical upward directional tracking. Selectable options include N or Y.*
- time format: Changes the clock visualization format between 12-hour and 24-hour systems.
- hour set: Manages the local system clock hours field value.
- min set: Manages the local system clock minutes field value.
- volume: Controls the global audio output level of the built-in buzzer alerts and key-press sound indicators, ranging from completely silent up to maximum loudness. The configurable range is from 0 to 8.
- factory reset: Reverts all global configurations, radio settings, and model lists back to the baseline factory defaults.(not include stick calibration)
- sw version: Displays the currently installed operating system or firmware version tag. This field is read-only and cannot be edited.

* Stick Calibration:

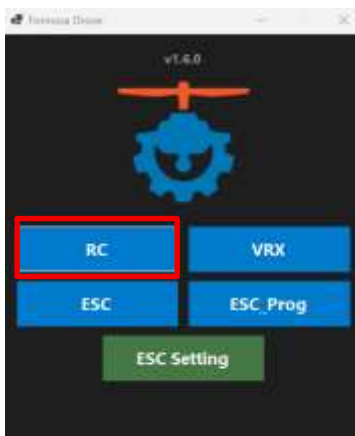
- a) Throttle: Move the throttle stick to around the 50% position (mid-point), then use the menu wheel to navigate to the vertical tracking channel depending on your stick mode (L stick vert.L/H for Mode 2 or R stick vert.L/H for Mode 1).
- b) Others: Keep all other stick axes centered.
- Set the throttle stick completely to 0% (Low) or 100% (High) and change the option to Y using the menu wheel (either action can be performed first), then press Enter to confirm.

```
System setup
model select      1
trim step         1
L stick hori.L
L stick hori.H
L stick vert.L
L stick vert.H
```

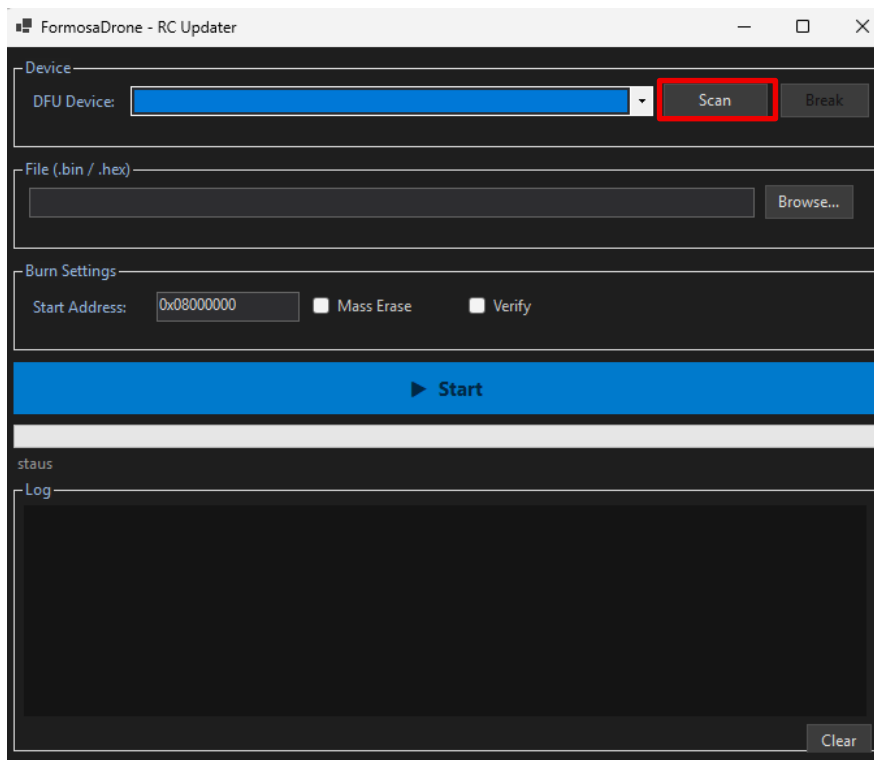
FIRMWARE UPDATE PROCEDURE

Follow these sequential steps to update the firmware on the RC-001 transmitter using the FormosaDrone tool:

1. Ensure that the RC-001 transmitter is powered off completely before starting the procedure.
2. Press and hold the physical Boot button on the transmitter hardware.
3. Connect the USB-C port of the RC-001 to your computer using a data cable, then release the Boot button once securely connected.
4. Launch the FormosaDrone software on your computer and select the "RC" option from the menu; the FormosaDrone RC Updater window will automatically pop up.

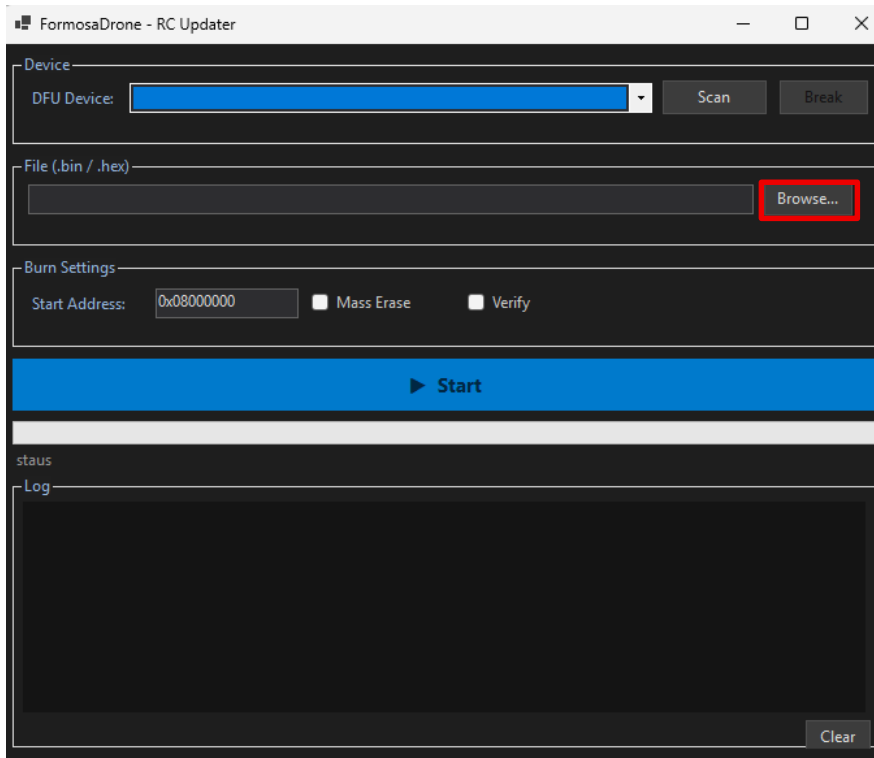


5. Click the "Scan" button to search for and detect the connected transmitter device.

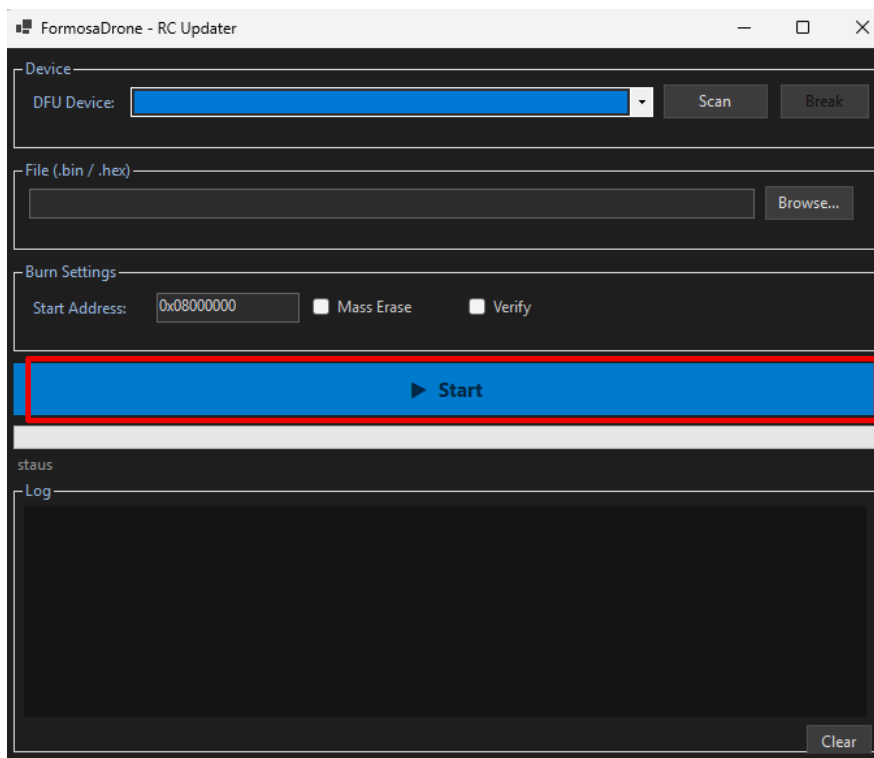


6. Click the "Browse" button to navigate and select the target firmware (.bin format) file you wish to

install.



7. Click the "Start" button to initiate the firmware flashing and update process.



8. Once the update sequence is completed successfully, you may unplug the USB-C cable from the transmitter.

WARRANTY

The SELLER warrants the **RC-001 Radio Control** to be free from defects in the material and workmanship for 1 year from the date of purchase from the SELLER or an authorized dealer. Should this product fail to be in good working order within 1 year warranty period, The SELLER, at its option, repair or replace the unit, provided that the unit has not been subjected to accident, disaster, abuse or any unauthorized modifications including static discharge and power surges.

Unit that fails under conditions other than those covered will be repaired at the current price of parts and labor in effect at the time of repair. Such repairs are warranted for 90 days from the day of reshipment to the BUYER. If the unit is delivered by mail, customers agree to insure the unit or assume the risk of loss or damage in transit. Under no circumstances will a unit be accepted without a return authorization number.

The warranty is in lieu of all other warranties expressed or implied, including without limitations, any other implied warranty or fitness or merchantability for any particular purpose, all of which are expressly disclaimed.

Proof of sale may be required in order to claim warranty. Customers outside Taiwan are responsible for shipping charges to and from the SELLER. Cables are limited to a 30 day warranty and cable must be free from any markings, scratches, and neatly coiled.

The content of this manual has been carefully checked and is believed to be accurate. However, The SELLER assumes no responsibility for any inaccuracies that may be contained in this manual. The SELLER will NOT be liable for direct, indirect, incidental, special, or consequential damages resulting from any defect or omission in this manual, even if advised of the possibility of such damages. **Also, the technical information contained herein regarding the RC-001 features and specifications is subject to change without further notice.**